

1. What does the following statement refer to?

A system that consists of symbols and processes is sufficient for intelligent action.

- a) Turing Test
- b) Total Turing Test
- c) Searle's Argument
- d) *The Physical Symbol System Hypothesis***
- e) Strong AI

2. Which of the following is a negative attribute of the Turing Test?

- a) Not a standard test
- b) Wide variety of required knowledge
- c) *Focuses on symbolic tasks***
- d) Easy to do in practice
- e) None of the above

3. Which of the following describes how a simple reflex agent works?

- a) Maintain a model of what the world is like and utility information about situations. Combine the world model and utility information to choose an action to perform.
- b) Maintain a model of what the world is like and goal information about desirable situations. Combine the world model and goal information to choose an action to perform.
- c) *Find a rule whose condition matches the current situation and perform the action associated with that rule.***
- d) Maintain a model of what the world is like to help find a rule whose condition matches the current situation. Perform the action associated with that rule.
- e) None of the above

4. What ability does a computer require in order to pass the Total Turing Test?

- a) Language
- b) Reasoning
- c) Vision
- d) *All of the above***
- e) Two of the above

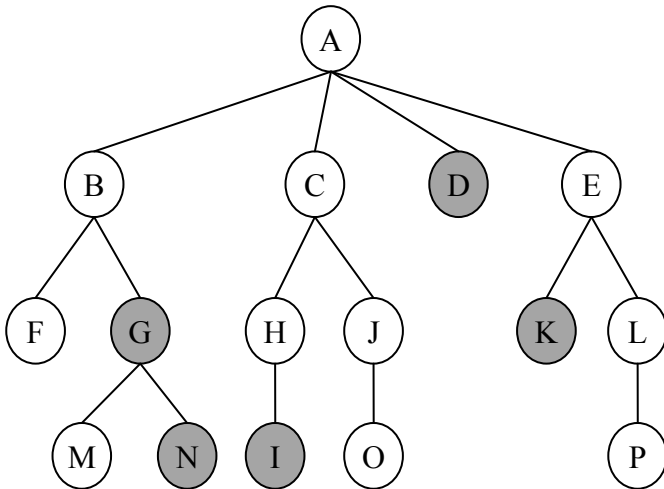
5. What does the following definition refer to?

The strategy is guaranteed to find a solution when there is one.

- a) *Completeness***
- b) Time Complexity
- c) Space Complexity
- d) Optimality
- e) None of the above

6. Which of the following is true about Depth First Search?
- Only complete if the limit is set to below the depth of the shallowest solution
 - Only complete in finite spaces with repeated state detection**
 - Only complete and optimal if the heuristic used is admissible
 - Always complete and optimal in finite search spaces
 - Never complete or optimal

The next two questions refer to the following tree:



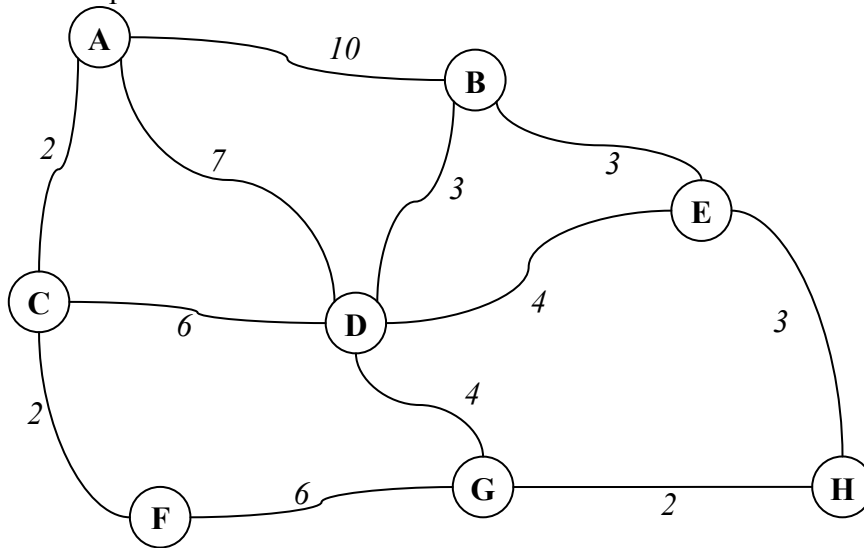
7. What order will the shaded nodes in the tree above be expanded using Breadth First Search?
- GNIDK
 - KDIGN
 - NIGKD
 - DGKNI**
 - DKGNI
8. What order will the shaded nodes in the tree above be expanded using Iterative Deepening Search?
- DGKNI
 - GNIDK
 - DDGKDGKNI
 - DKDGKDGIN
 - DGDKGNIDK**
9. Which node in the fringe does A* search expand first?
- The node closest to the goal as given by the heuristic function
 - The node on the least-cost solution path as given by the heuristic and cost function**
 - The node that will always lead to the optimal path
 - Options b and c
 - None of the above

10. Heuristic H1 is admissible if:

- a) The effective branching factor is close to the branching factor for the problem
- b) $H1(n)$ is equal to the path cost to the goal for all n
- c) $H1(n)$ is larger than or equal to the path cost to the goal for all n
- d) $H1(n)$ is smaller than or equal to the path cost to the goal for all n**
- e) None of the above

The next two questions refer to the following map and table:

Map showing states and path costs:



Heuristic values of states:

A	10	E	3
B	5	F	6
C	8	G	2
D	4	H	0

11. With the initial state being A and the goal state being H, what are the first four nodes, in order, that will be expanded using Greedy Search?

- a) ABEH
- b) ACBD
- c) ADEH
- d) ADGH**
- e) ACFD

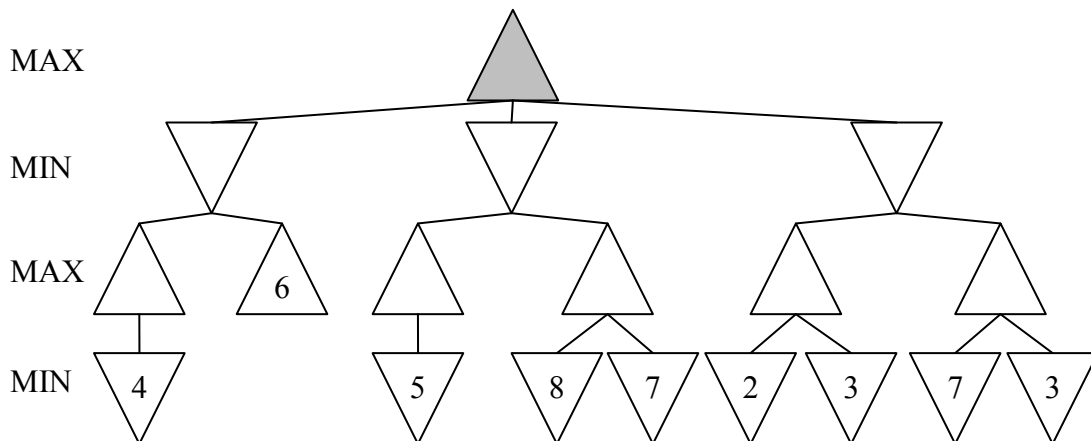
12. With the initial state being A and the goal state being H, what are the first four nodes, in order, that will be expanded using A* Search?

- a) ABEH
- b) ACBD
- c) ADEH
- d) ADGH
- e) ACFD**

13. Which of the following is a definition of effective branching factor?

- a) The set of legal states resulting from actions applied to the current state
- b) The average number of states that can be reached from any given state
- c) The depth of the least-cost solution
- d) The branching factor of the game tree when the successor function does not permit the generation of paths with cycles in them
- e) **The branching factor that a uniform tree with the depth of the solution found would have in order to contain one more than the number of nodes generated during the search**

The next two questions refer to the following game tree:



14. In the game tree above, what is the MiniMax value of the initial (shaded) node?

- a) 3
- b) 4
- c) **5**
- d) 6
- e) 7

15. In the game tree above, how many times will a branch be pruned using alpha-beta pruning?

- a) 0
- b) 1
- c) **2**
- d) 3
- e) 4

16. In adversarial search, a utility function provides a value for:

- a) **A terminal state**
- b) An initial state
- c) Whether the game is over
- d) A MAX node
- e) An intermediate state

17. Which of the following terms refers to a search to a depth where the heuristic value stops changing so much?

- a) **Quiescence**
- b) Horizon effect
- c) Evaluation function
- d) Cut-off
- e) Alpha-beta pruning

18. An agent can be considered rational if it chooses what action to perform by using:

- a) Probability theory
- b) Utility theory
- c) **Decision theory**
- d) Degree of belief
- e) Marginalisation

19. If Variable Y causes Variable X, which of the following statements is true?

- a) X and Y are independent
- b) **X and Y are not independent**
- c) X and Y are conditionally independent
- d) There is not enough information to determine the relationship between X and Y
- e) None of the above

20. Which of the following is a definition of conditional probability:

- a) Summing out all other variables from any joint distribution
- b) **The probability of a proposition given that all we know is a given fact**
- c) Knowledge of one variable does not affect knowledge of another variable
- d) The probability of a proposition in the absence of any other information
- e) None of the above

End of paper